

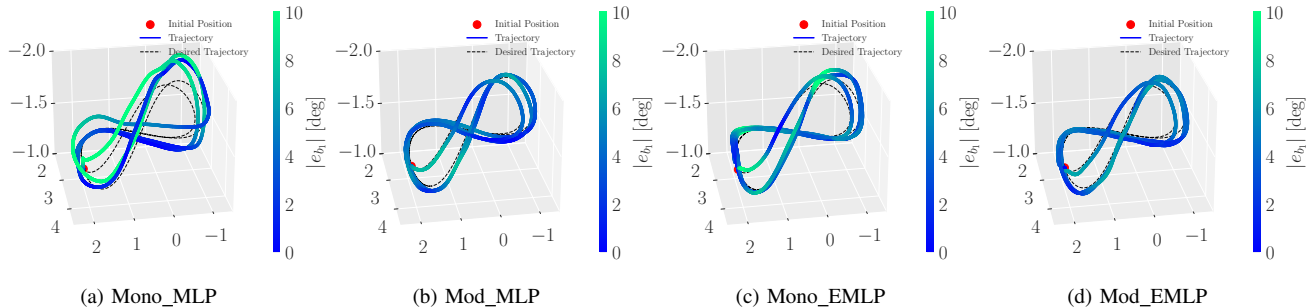


Fig. 7. Real-world flight trajectory of different frameworks corresponding to Table III results. Each plot depicts three laps starting from the same location (red dot), with the reference trajectory shown as black dotted curves. The yawing errors are visualized using a colormap, where blue hues correspond to smaller errors and green hues to larger errors.